

C-843 DC-Servo-Motor Controller Servo Motion Controller/Driver PCI Board for 2 or 4 Axes



C-843.41 DC-motor controller board with M-110.DG linear stage, M-235.5DG heavy duty linear actuator, M-511.DD direct drive translation stage and M-501.1DG vertical stage. No external amplifier is required to drive any of these or other PI stages. Small motors are driven through the C-843's onboard linear amplifiers, direct-drive PI stages (e.g. M-511.DD) employ ActiveDrive™ controlled off the C-843's PWM outputs.

- Two and Four Axis Version
- Very Cost-Effective: Servo Amplifiers On-Board
- Additional PWM Outputs for High-Power Motors
- Trapezoidal Curve, S-Curve and Velocity Profile
- 32 kSamples RAM for High-Speed Buffer Operations
- 16 I/O Lines for Flexible Automation
- Fast PCI Communication, 120 µs for Position Read
- Motor-Brake Control Output
- Extensive Software Support
- General Command Set (GCS) Compatible

The C-843 PCI motion controller card drives up to 4 axes of micropositioning equipment. Because there is no need for external servo-amplifiers, this new card is a very cost-effective, easy-to-set-up solution.

On-Board Servo-Amplifiers

Unlike other PCI controller cards, the new C-843 comes with on-board, low-noise linear amplifiers for the small DC motors used in most compact micropositioning stages and actuators.

In addition, PWM outputs are available to drive more powerful equipment (all direct-drive

translation and rotation stages from PI feature the integrated ActiveDrive™ PWM amplifiers, and also connect to the C-843 with no external power amplifiers).

The PWM mode and linear amplifier mode can be programmed individually for each of the 4 (or 2) channels.

High-Performance PID Control

The C-843 employs a fast DSP (digital signal processor) providing high-performance PID motion control with many options for trajectory generation and filter settings for superior positioning and tra-

cking accuracy. Position, velocity, acceleration and several other motion parameters can be programmed individually for each axis on-the-fly. High-bandwidth counters (5 MHz) support differential encoder feedback (incremental rotary encoders or linear scales) for fast and accurate positioning.

I/O for Flexible Automation

In addition to 3 TTL inputs per channel for limit and reference signals, 16 more I/O lines are available for flexible automation tasks (trigger functions, etc.). The C-843 also features motor-brake output lines (e.g. for M-531.DDB stages).

High-Speed Buffering

The integrated 32 k-sample trace memory allows online buffering (read and write) at integer multiples of the servo-loop time of up to four independent system variables (positions, velocities, internal register contents, etc.) This allows the observation of the motion system and also performing customized trajectory profiles.

PI General Command Set (GCS)

The comprehensive command structure is based on the PI General Command Set (GCS). With GCS the development of custom application programs is simplified, because the commands for all supported devices are identical in syntax and function. PI controllers for nanopositioning systems, for piezomotors and servo or stepper motors can be commanded with GCS.

Software / Programming

In addition to the user software for setup, system optimization and operation, comprehensive LabVIEW and DLL libraries are

Ordering Information

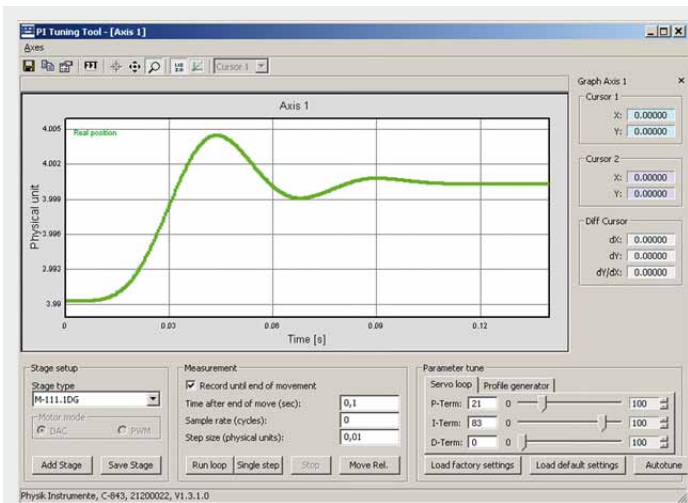
- C-843.21**
DC-Motor Controller PCI PC Board, 2-Axis
- C-843.41**
DC-Motor Controller PCI PC Board, 4-Axis
- C-843.JS**
Joystick and PCI Interface Board for C-843 Motor Controller

provided. The user friendly PI MikroMove™ provides a convenient interface for stage operation including tuning tool, joystick operation, terminal and macro editor.

Communications to/from the board consist of packet-based messages passed via memory access. An interrupt line is provided so that the chipset can signal the PC when special conditions arise, such as reception of an encoder index pulse. For system programmers the C-843 offers direct access to the DSP.

	Stage	jk	<	Target	>	>	Step size	Position	HALT	State	Velocity	Servo
1	M-235.5DD	jk	<	0.000000	>	>	0.100000	0.000000	HALT	on target	15.000000	✓
2	M-605.2DD	jk	<	100.0000	>	>	0.1000	100.0000	HALT	unreferenced	25.000000	?
3	M-511.PD	jk	<	56.00000	>	>	1.0000	56.00000	HALT	on target	62.500000	✓
4	M-110.1DG	jk	<	0.000000	>	>	0.010000	0.000000	HALT	on target	1.000000	✓

PIMikroMove® tabular presentation of four connected axes with display of absolute and relative positioning input, current position, halt axis button, state and velocity setting.



The Tuning Tool which is integrated in PIMikroMove® demonstrates acquiring and displaying step and settle data of micropositioning systems. Controls allow adjustment of the PID parameters for best performance.

Technical Data

Model	C-843
Function	PC plug-in DC-servo-motor controller board, 32-bit plug-and-play PCI-bus interface, supported by main boards with 3.3 V and 5 V PCI bus connectors (universal card)
Axes	2 (C-843.21); 4 (C-843.41)
Servo characteristics	Programmable PID V-ff filter, parameter changes on-the-fly
Profile modes	Trapezoidal, S-curve, velocity profile
Output power / resolution	Analog 6 watts/channel (drawn directly from PC power supply), 12-bit D/A converters, PWM 10-bit, 24.5 kHz
Current limitation	500 mA per channel (short-circuit-proof)
Encoder input	AB (quadrature) differential TTL signals, 5×10^6 counts/s
Stall detection	Servo off, triggered by programmable position error
Limit switches	2 TTL / axis (active high/low, programmable)
Reference switches	1 TTL / axis (active high/low, programmable)
I/O ports	8 TTL inputs, 8 TTL outputs
Motor connectors	15-pin (f) sub-D per channel (2 on board + 2 on bracket for C-843.41)
Interface/communication	PC PCI bus
Command set	PI General Command Set (see p. A-11)

Linear Actuators & Motors

Nanopositioning / Piezoelectrics

Nanometrology

Micropositioning

Hexapod 6-Axis Systems / Parallel Kinematics

Linear Stages

Translation (X)

Vertical (Y)

Multi-Axis

Rotary & Tilt Stages

Accessories

Servo & Stepper Motor Controllers

Single-Channel

Hybrid

Multi-Channel

Micropositioning Fundamentals

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