## High-Resolution Linear Actuator

## Suitable for High Cycle Numbers

L-220<br>- Forces to 125 N<br>- Travel ranges 13 to 77 mm (1⁄2" to 3")<br>- DC or stepper motor<br>- Vacuum-compatible variants available

## Reference-class linear drive

Combines high precision, high forces, and high dynamics. Versions available for vacuum environments to $10^{-9} \mathrm{hPa}$.
High-quality components
Ball screw for smooth feed. Nonrotating tip for uniform motion prevents wobble, torque, and wear at the point of contact. Incl. flat and spherical tip for decoupling forces. Noncontact limit switches protect the mechanics. A direction-sensing reference switch supports automation applications. Position-controlled variants with differential encoder driver in the connector for safe signal transfer over distances up to 10 m .

## Motor variants

- Position-controlled DC motors with a gearhead and high-resolution rotary encoders allow for incremental motion of just 100 nm
- High-performance and low-vibration 2-phase stepper motors with gear ratio allow precision positioning even without position control


## Application fields

Research. Automation. Optical alignment.

| Motion | Unit | L-220.10DG | L-220.20DG | L-220.50DG | L-220.70DG | L-220.10SG | L-220.20SG | L-220.50SG | L-220.70SG |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Active axes |  | X | X | X | X | X | X | X | X |
| Travel range in X | mm | 13 | 26 | 52 | 77 | 13 | 26 | 52 | 77 |
| Maximum velocity in X , unloaded | $\mathrm{mm} / \mathrm{s}$ | 3.5 | 3.5 | 3.5 | 3.5 | 0.8 | 0.8 | 0.8 | 0.8 |


| Positioning | Unit | Tolerance | L-220.10DG | L-220.20DG | L-220.50DG | L-220.70DG | L-220.10SG | L-220.20SG | L-220.50SG | L-220.70SG |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unidirectional repeatability in $X$ | $\mu \mathrm{m}$ | Typ. | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 |
| Bidirectional repeatability in X | $\mu \mathrm{m}$ | Typ. | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ |
| Minimum incremental motion in X | $\mu \mathrm{m}$ | Typ. | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 |
| Reference switch |  |  | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN |
| Limit switches |  |  | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, <br> N/C con- <br> tact, 5 V , <br> NPN | Hall effect, N/C contact, 5 V , NPN | Hall effect, N/C contact, 5 V , NPN |
| Motor encoder |  |  | Incremental rotary encoder | Incremental rotary encoder | Incremental rotary encoder | Incremental rotary encoder |  |  |  |  |
| Resolution, motor encoder | Cts./rev. |  | 512 | 512 | 512 | 512 |  |  |  |  |
| Motor encoder: Sensor signal |  |  | A/B quadrature, RS- $422$ | A/B quadrature, RS422 | A/B quadrature, RS422 | $A / B$ quadrature, RS422 |  |  |  |  |


| Drive Properties | Unit | Tolerance | L-220.10DG | L-220.20DG | L-220.50DG | L-220.70DG | L-220.10SG | L-220.20SG | L-220.50SG | L-220.70SG |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drive type |  |  | DC gear motor | DC gear motor | DC gear motor | DC gear motor | 2-phase stepper motor with gearhead | 2-phase stepper motor with gearhead | 2-phase stepper motor with gearhead | 2-phase stepper motor with gearhead |
| Maximum power consumption | W |  | 4 | 4 | 4 | 4 |  |  |  |  |
| Motor resolution | Full steps/ rev. |  |  |  |  |  | 24 | 24 | 24 | 24 |
| Nominal voltage | V |  | 12 | 12 | 12 | 12 | 3.5 | 3.5 | 3.5 | 3.5 |
| Nominal current, RMS | A | Typ. | 0.28 | 0.28 | 0.28 | 0.28 | 0.25 | 0.25 | 0.25 | 0.25 |
| Peak current, RMS | A | Typ. | 0.56 | 0.56 | 0.56 | 0.56 |  |  |  |  |
| Drive force in negative direction of motion in X | N | Typ. | 125 | 125 | 125 | 125 | 125 | 125 | 125 | 125 |
| Drive force in positive direction of motion in X | N | Typ. | 125 | 125 | 125 | 125 | 125 | 125 | 125 | 125 |
| Torque constant | N.m/A | Typ. | 0.0115 | 0.0115 | 0.0115 | 0.0115 |  |  |  |  |
| Resistance phase-phase | $\Omega$ | Typ. | 19.8 | 19.8 | 19.8 | 19.8 | 12.5 | 12.5 | 12.5 | 12.5 |
| Inductance phase-phase | mH |  | 0.42 | 0.42 | 0.42 | 0.42 | 6.3 | 6.3 | 6.3 | 6.3 |
| Back EMF, phase-phase, rotational | V/kRPM | Max. | 1.21 | 1.21 | 1.21 | 1.21 | 11 | 11 | 11 | 11 |
| Number of pole pairs |  |  | 1 | 1 | 1 | 1 |  |  |  |  |


| Mechanical Properties | Unit | Tolerance | L-220.10DG | L-220.20DG | L-220.50DG | L-220.70DG | L-220.10SG | L-220.20SG | L-220.50SG | L-220.70SG |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drive screw type |  |  | Ball screw | Ball screw | Ball screw | Ball screw | Ball screw | Ball screw | Ball screw | Ball screw |
| Drive screw pitch | mm |  | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Gear ratio i |  |  | 12493:567 | 12493:567 | 12493:567 | 12493:567 | $\begin{aligned} & 387283: \\ & 5103 \end{aligned}$ | $\begin{aligned} & 387283: \\ & 5103 \end{aligned}$ | $\begin{aligned} & 387283 \text { : } \\ & 5103 \end{aligned}$ | $\begin{aligned} & 387283: \\ & 5103 \end{aligned}$ |
| Holding force in X , passive | $N$ |  |  |  |  |  | 125 | 125 | 125 | 125 |
| Moved mass in X , unloaded | g |  | 20 | 20 | 25 | 30 | 20 | 20 | 25 | 30 |
| Permissible push force in Y | N | Max. | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Overall mass | g |  | 210 | 230 | 260 | 290 | 230 | 250 | 280 | 320 |
| Material |  |  | Stainless steel, bronze | Stainless steel, bronze | Stainless steel, bronze | Stainless steel, bronze | Stainless steel, bronze | Stainless <br> steel, bron- <br> ze | Stainless steel, bronze | Stainless steel, bronze |


| Miscellaneous | Unit | L-220.10DG | L-220.20DG | L-220.50DG | L-220.70DG | L-220.10SG | L-220.20SG | L-220.50SG | L-220.70SG |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating temperature range | ${ }^{\circ} \mathrm{C}$ | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 |
| Connector |  | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) |
| Cable length | m | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 |
| Recommended controllers / drivers |  | C-863 <br> C-885 with <br> C-863. <br> $20 C 885$ <br> C-884 <br> ACS modu- <br> lar controller | C-863 <br> C-885 with <br> C-863. <br> $20 C 885$ <br> C-884 <br> ACS modu- <br> lar controller | C-863 <br> C-885 with <br> C-863. <br> $20 C 885$ <br> C-884 <br> ACS modu- <br> lar controller | C-863 <br> C-885 with <br> C-863. <br> $20 C 885$ <br> C-884 <br> ACS modu- <br> lar control- <br> ler | C-663.12 <br> C-885 with C-663. <br> 12C885 <br> ACS modu- <br> lar controller | C-663.12 <br> C-885 with C-663. <br> 12C885 <br> ACS modu- <br> lar controller | C-663.12 <br> C-885 with C-663. <br> 12C885 <br> ACS modu- <br> lar controller | C-663.12 <br> C-885 with <br> C-663. <br> 12 C 885 <br> ACS modu- <br> lar control- <br> ler |

## Drawings / Images



|  | Travel | A | B | C |
| :---: | :---: | :---: | :---: | :---: |
| L-220.10SG | 13 | 26 | 148,3 | 13 |
| L-220.10DG | 13 | 26 | 155,2 | 19,9 |
| L-220.20SG | 26 | 39 | 161,5 | 13 |
| L-220.20DG | 26 | 39 | 168,4 | 19,9 |
| L-220.50SG | 52 | 65 | 186,6 | 13 |
| L-220.50DG | 52 | 65 | 193,5 | 19,9 |
| L-220.70SG | 77 | 90 | 211,6 | 13 |
| L-220.70DG | 77 | 90 | 218,5 | 19,9 |

L-220, dimensions in mm

## Drawings / Images



L-220 linear actuators are available in various length versions and with DC or stepper motor with gearhead


## Order Information

## L-220.10DG

High-resolution linear actuator, DC gear motor, 13 mm travel range, 125 N feed force; $3.5 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 512 counts/rev. resolution, A/B quadrature, RS-422; limit switch: Hall effect, N/C contact, 5 V, NPN; 0.5 m cable length

## L-220.20DG

High-resolution linear actuator, DC gear motor, 26 mm travel range, 125 N feed force; $3.5 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 512 counts/rev. resolution, A/B quadrature, RS-422; limit switch: Hall effect, N/C contact, $5 \mathrm{~V}, \mathrm{NPN}$; 0.5 m cable length

## L-220.50DG

High-resolution linear actuator, DC gear motor, 52 mm travel range, 125 N feed force; $3.5 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 512 counts/rev. resolution, A/B quadrature, RS-422; limit switch: Hall effect, N/C contact, $5 \mathrm{~V}, \mathrm{NPN}$; 0.5 m cable length

## L-220.70DG

High-resolution linear actuator, DC gear motor, 77 mm travel range, 125 N feed force; $3.5 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 512 counts/rev. resolution, A/B quadrature, RS-422; limit switch: Hall effect, N/C contact, $5 \mathrm{~V}, \mathrm{NPN}$; 0.5 m cable length

## L-220.10SG

High-resolution linear actuator; 2-phase stepper motor with gearhead; 13 mm travel range; 125 N feed force; $0.8 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; limit switch: Hall effect, N/C contact, $5 \mathrm{~V}, \mathrm{NPN} ; 0.5$ cable length

## L-220.20SG

High-resolution linear actuator; 2-phase stepper motor with gearhead; 26 mm travel range; 125 N feed force; $0.8 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; limit switch: Hall effect, N/C contact, $5 \mathrm{~V}, \mathrm{NPN} ; 0.5$ cable length

## L-220.50SG

High-resolution linear actuator; 2-phase stepper motor with gearhead; 52 mm travel range; 125 N feed force; $0.8 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; limit switch: Hall effect, $\mathrm{N} / \mathrm{C}$ contact, $5 \mathrm{~V}, \mathrm{NPN} ; 0.5$ cable length

## L-220.70SG

High-resolution linear actuator; 2-phase stepper motor with gearhead; 77 mm travel range; 125 N feed force; $0.8 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; limit switch: Hall effect, $\mathrm{N} / \mathrm{C}$ contact, $5 \mathrm{~V}, \mathrm{NPN} ; 0.5 \mathrm{~m}$ cable length

