## High-Load Linear Actuator

## Dynamic, High-Resolution Precision Drive with DC or Stepper Motor



## L-239

- High drive force up to 300 N
- Travel range 52 mm (2")
- Minimum incremental motion $0.1 \mu \mathrm{~m}$
- Velocity to $50 \mathrm{~mm} / \mathrm{s}$
- Preloaded, low-friction ball screw


## Product overview

High-resolution high-load linear actuator. Stepper motor for high torque. Highly dynamic, closed-loop DC and BLDC motors for high velocities. Robust design for industrial environments.

## High-quality components

- Ground ball screw for high velocities
- Low-friction output shaft bearing can handle lateral forces to 100 N
- Nonrotating tip for uniform motion prevents wobble, torque, and wear at the point of contact
- Contactless limit switches protect the mechanics, a direction-sensing reference switch simplifies automation tasks
- Optional on request and at additional charge: Increase of drive force to 1000 N .


## Application fields

Research. Automation. Optical alignment.

| Motion | Unit | L-239.033232 | L-239.035232 | L-239.50AD | L-239.50SD |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Active axes |  | X | X | X | X |
| Travel range in X | mm | 52 | 52 | 52 | 52 |
| Maximum velocity in $X$, unloaded | $\mathrm{mm} / \mathrm{s}$ | 50 | 50 | 50 | 25 |


| Positioning | Unit | Tolerance | L-239.033232 | L-239.035232 | L-239.50AD | L-239.50SD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Integrated sensor |  |  | Incremental rotary encoder | Incremental rotary encoder | Incremental rotary encoder |  |
| Unidirectional repeatability in X | $\mu \mathrm{m}$ | Typ. | 0.2 | 0.2 | 0.2 | 0.1 |
| Bidirectional repeatability in X | $\mu \mathrm{m}$ | Typ. | $\pm 1$ | $\pm 1$ | $\pm 1$ | $\pm 1$ |
| Minimum incremental motion in X | $\mu \mathrm{m}$ | Typ. | 0.2 | 0.2 | 0.2 | 0.1 |
| Sensor signal |  |  | A/B quadrature, RS-422 | A/B quadrature, RS-422 | A/B quadrature, RS-422 |  |
| Sensor resolution | Cts./rev. |  | 20000 | 20000 | 20000 |  |
| Reference switch |  |  | Hall effect, N/C contact, 5 V, NPN | Hall effect, N/C contact, 5 V, NPN | Hall effect, N/C contact, 5 V, TTL | Hall effect, N/C contact, 5 V, NPN |
| Limit switches |  |  | Hall effect, N/C contact, 5 V, NPN | Hall effect, N/C contact, 5 V, NPN | Hall effect, N/C contact, 5 V, TTL | Hall effect, N/C contact, 5 V, NPN |


| Drive Properties | Unit | Tolerance | L-239.033232 | L-239.035232 | L-239.50AD | L-239.50SD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Drive type |  |  | DC motor | Brushless DC motor | DC motor with ActiveDrive | 2-phase stepper motor |
| Motor resolution | Full steps/ rev. |  |  |  |  | 200 |
| Nominal voltage | V |  | 24 | 24 | 24 | 24 |
| Peak voltage | V |  | 48 | 48 | 24 | 48 |
| Drive force in positive direction of motion in X | N | Typ. | 300 | 300 | 300 | 300 |
| Drive force in negative direction of motion in $X$ | N | Typ. | 300 | 300 | 300 | 300 |


| Mechanical Properties | Unit | Tolerance | L-239.033232 | L-239.035232 | L-239.50AD | L-239.50SD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Guide |  |  | Recirculating ball bearing guide | Recirculating ball bearing guide | Recirculating ball bearing guide | Recirculating ball bearing guide |
| Drive screw type |  |  | Ball screw | Ball screw | Ball screw | Ball screw |
| Drive screw pitch | mm |  | 1 | 1 | 1 | 1 |
| Holding force in $X$, passive | N |  | 40 | 40 | 40 | 80 |
| Moved mass in X, unloaded | g |  | 155 | 155 | 155 | 155 |
| Permissible push force in Y | N | Max. | 10 | 10 | 10 | 10 |
| Overall mass | g |  | 1750 | 1750 | 1720 | 1650 |
| Material |  |  | Aluminum, stainless steel | Aluminum, stainless steel | Aluminum, stainless steel | Aluminum, stainless steel |


| Miscellaneous | Unit | L-239.033232 | L-239.035232 | L-239.50AD | L-239.50SD |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Operating temperature range | ${ }^{\circ} \mathrm{C}$ | 5 to 40 | 5 to 40 | 5 to 40 | 5 to 40 |
| Connector |  | HD D-sub 26-pin (m) | HD D-sub 26-pin (m) | D-sub 15-pin (m) | HD D-sub 26-pin (m) |
| Connector for supply voltage |  |  |  | M8 4-pin (m) |  |
| Recommended controllers / drivers |  | $\begin{aligned} & \text { C-863 } \\ & \text { C-885 with C-863.20C885 } \\ & \text { C-884 } \\ & \text { Modular ACS controller } \end{aligned}$ | C-891 <br> C-885 with C-891.11C885 <br> Modular ACS controller | $\begin{aligned} & \text { C-863 } \\ & \text { C-885 with C-863.20C885 } \\ & \text { C-884 } \end{aligned}$ | C-663.12 <br> C-885 with C-663.12C885 <br> Modular ACS controller |

## Drawings / Images



L-239.03 $\times 232$, dimensions in mm . Note that a comma is used in the drawings instead of a decimal point.

## Drawings / Images



L-239.50AD, dimensions in mm. Note that a comma is used in the drawings instead of a decimal point.

## Drawings / Images



L-239.50SD, dimensions in mm. Note that a comma is used in the drawings instead of a decimal point.

## Order Information

## L-239.033232

High-load linear actuator; DC motor; 52 mm travel range; 300 N feed force; $50 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 20000 counts/rev. sensor resolution, A/B quadrature, RS-422; limit switches: Hall effect, opener, 5 V, NPN

## L-239.035232

High-load linear actuator; brushless DC motor; 52 mm travel range; 300 N feed force; $50 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 20000 counts/rev. sensor resolution, $A / B$ quadrature, RS-422; limit switches: Hall effect, opener, 5 V, NPN

## L-239.50AD

High-load linear actuator; DC motor with ActiveDrive; 52 mm travel range; 300 N feed force; $50 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; incremental rotary encoder, 20000 counts/rev. sensor resolution, A/B quadrature, RS-422; limit switches: Hall effect, opener, 5 V , TTL

## L-239.50SD

High-load linear actuator; 2-phase stepper motor; 52 mm travel range; 300 N feed force; $25 \mathrm{~mm} / \mathrm{s}$ maximum velocity; ball screw; limit switches: Hall effect, opener, 5 V , NPN

